

# Bevezetés a matematikába

Járai Antal

Ezek a programok csak szemléltetésre szolgálnak.

- ▶ 1. Halmazok
- ▶ 2. Természetes számok
- ▶ 3. A számfogalom bővítése
- ▶ 4. Véges halmazok
- ▶ 5. Végtelen halmazok
- ▶ 6. Számelmélet
- ▼ 7. Gráfelmélet

- ▼ 7.1. Irányítatlan gráfok

- ▼ 7.1.1. Irányítatlan gráfok.

```
> restart;
```

```
> with(networks);
```

```
[acycpoly, addedge, addvertex, adjacency, allpairs, ancestor, arrivals, (7.1.1.1)  
bicomponents, charpoly, chrompoly, complement, complete,  
components, connect, connectivity, contract, countcuts, counttrees,  
cube, cycle, cyclebase, daughter, degreeseq, delete, departures,  
diameter, dinic, djspanntree, dodecahedron, draw, draw3d,  
duplicate, edges, ends, eweight, flow, flowpoly, fundcyc, getlabel,  
girth, graph, graphical, gsimp, gunion, head, icosahedron,  
incidence, incident, indegree, induce, isplanar, maxdegree,  
mincut, mindegree, neighbors, new, octahedron, outdegree, path,  
petersen, random, rank, rankpoly, shortpathtree, show, shrink,
```

*span, spanpoly, spantree, tail, tetrahedron, tuttepoly, vdegree, vertices, void, vweight]*

```
> new(G1):addvertex({v1,v2,v3,v4,v5},G1);
addedge([ {v1,v2}, {v1,v2}, {v1,v4}, {v3,v4}, {v4,v4} ],G1);
edges(G1);vertices(G1);
ends(e2,G1);
edges({v1,v2},G1);
incident(v1,G1);incident(v5,G1);
neighbors(v1,G1);neighbors(v4,G1);
```

```
v1, v2, v3, v5, v4
e1, e2, e3, e4, e5
{e1, e2, e3, e4, e5}
{v1, v2, v3, v5, v4}
{v1, v2}
{e1, e2}
{e1, e2, e3}
{ }
{v2, v4}
{v1, v3, v4}
```

(7.1.1.2)

```
> vdegree(v1,G1);vdegree(v4,G1);vdegree(v5,G1);degreeseq(G1);
mindegree(G1);maxdegree(G1);
```

```
3
3
0
[0, 1, 2, 3, 3]
```

```
0
3
```

(7.1.1.3)

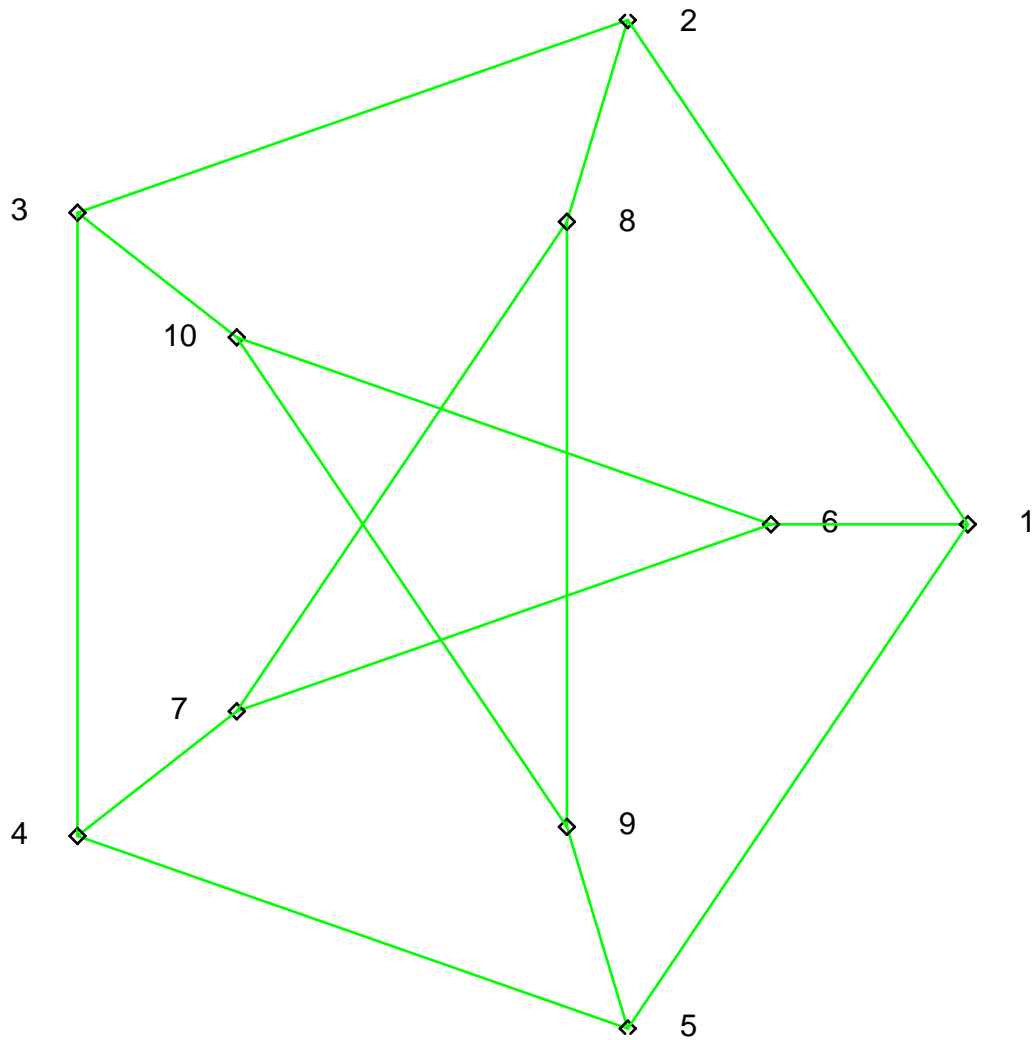
```
> show(G1);
```

```
table([_Tail = table([ ]), _Counttrees = _Counttrees, _Vertices = ({v1, (7.1.1.4)
v2, v3, v5, v4}), _Vweight = table(sparse, [ ]),
_EdgeIndex = table(symmetric, [(v3, v4) = {e4}, (v1, v4) = {e3},
v4 = {e5}, (v1, v2) = ({e1, e2})]),
_Econnectivity = _Econnectivity, _Emaxname = 5,
_Head = table([ ]), _Eweight = table([e4 = 1, e1 = 1, e5 = 1,
e2 = 1, e3 = 1]), _Edges = ({e1, e2, e3, e4, e5}),
_Neighbors = table([v4 = ({v1, v3, v4}), v5 = {}, v2 = {v1},
v3 = {v4}, v1 = ({v2, v4})]), _Status = ({MULTIGRAPH,
LOOPS}), _Ends = table([e4 = ({v3, v4}), e1 = ({v1, v2}),
e5 = {v4}, e2 = ({v1, v2}), e3 = ({v1, v4})]),
_Bicomponents = _Bicomponents, _Countcuts = _Countcuts])
```

```

> G:=void(10):vertices(G);edges(G);
  addedge([{1,2},{2,3},{3,4}],names=[cica,alma,kutya],G);show
  (G);
      {1, 2, 3, 4, 5, 6, 7, 8, 9, 10}
      { }
      cica, alma, kutya
table([_Tail = table([]), _Counttrees = _Counttrees, _Vertices = ({1, (7.1.1.5)
  2, 3, 4, 5, 6, 7, 8, 9, 10}), _Vweight = table(sparse, []),
  _EdgeIndex = table(symmetric, [(3, 4) = {kutya}, (2,
  3) = {alma}, (1, 2) = {cica}])), _Econnectivity = _Econnectivity,
  _Head = table([]), _Eweight = table([alma = 1, kutya = 1,
  cica = 1]), _Edges = ({cica, alma, kutya}),
  _Neighbors = table([1 = {2}, 2 = ({1, 3}), 3 = ({2, 4}), 5 = {},
  4 = {3}, 7 = {}, 6 = {}, 10 = {}, 8 = {}, 9 = {}]),
  _Ends = table([alma = ({2, 3}), kutya = ({3, 4}), cica = ({1,
  2})]), _Bicomponents = _Bicomponents,
  _Countcuts = _Countcuts])
> G:=petersen():draw(G);degreeseq(G);

```

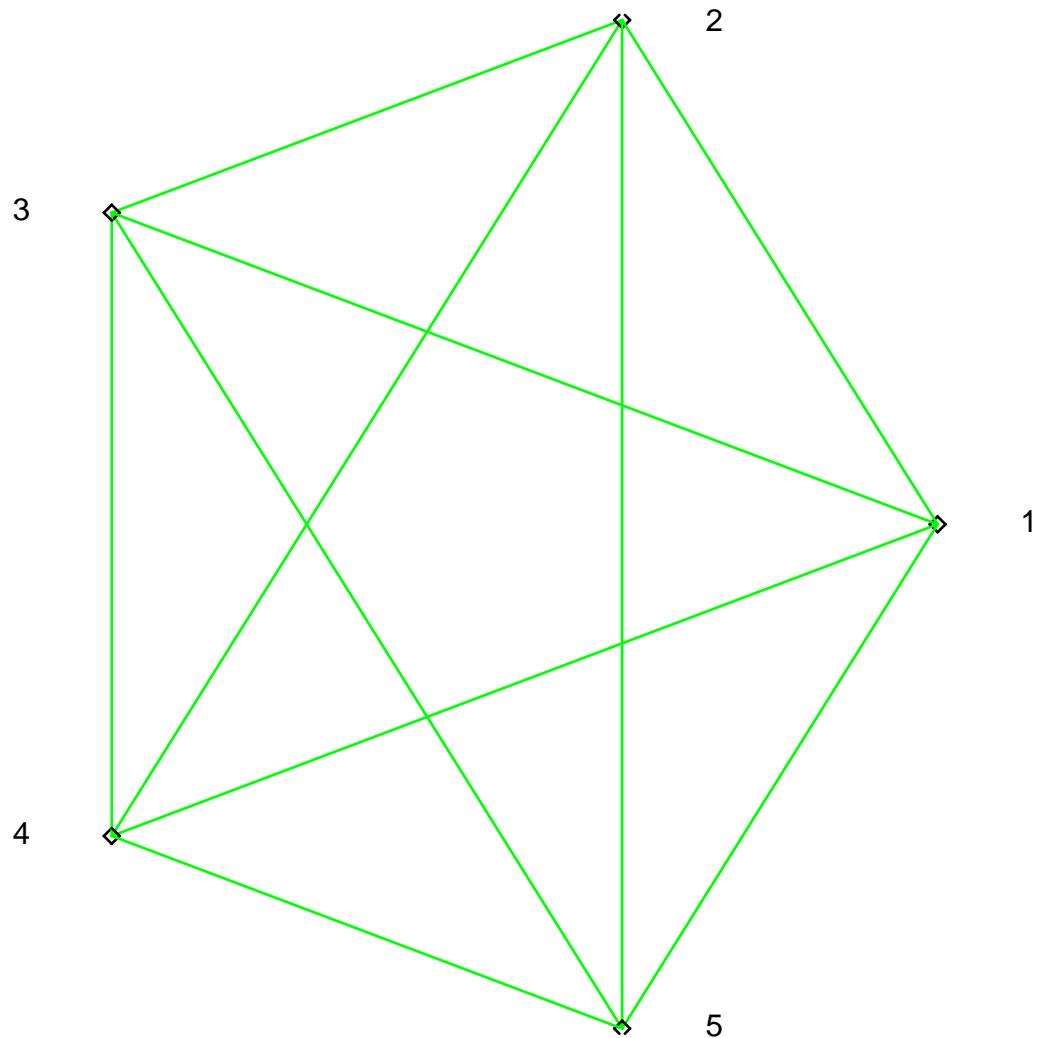


[3, 3, 3, 3, 3, 3, 3, 3, 3, 3]

(7.1.1.6)

- ▶ -> 7.1.2. Feladat.
- ▶ 7.1.3. Feladat.
- ▶ 7.1.4. Feladat.
- ▶ 7.1.5. Feladat.
- ▶ \*7.1.6. Feladat.
- ▼ 7.1.7. Gráfok izomorfiaja.
- ▼ 7.1.8. Példák.

```
> G21:=complete(5):draw(G21);
```



▼ **7.1.9. Gráfok Descartes-szorzata.**

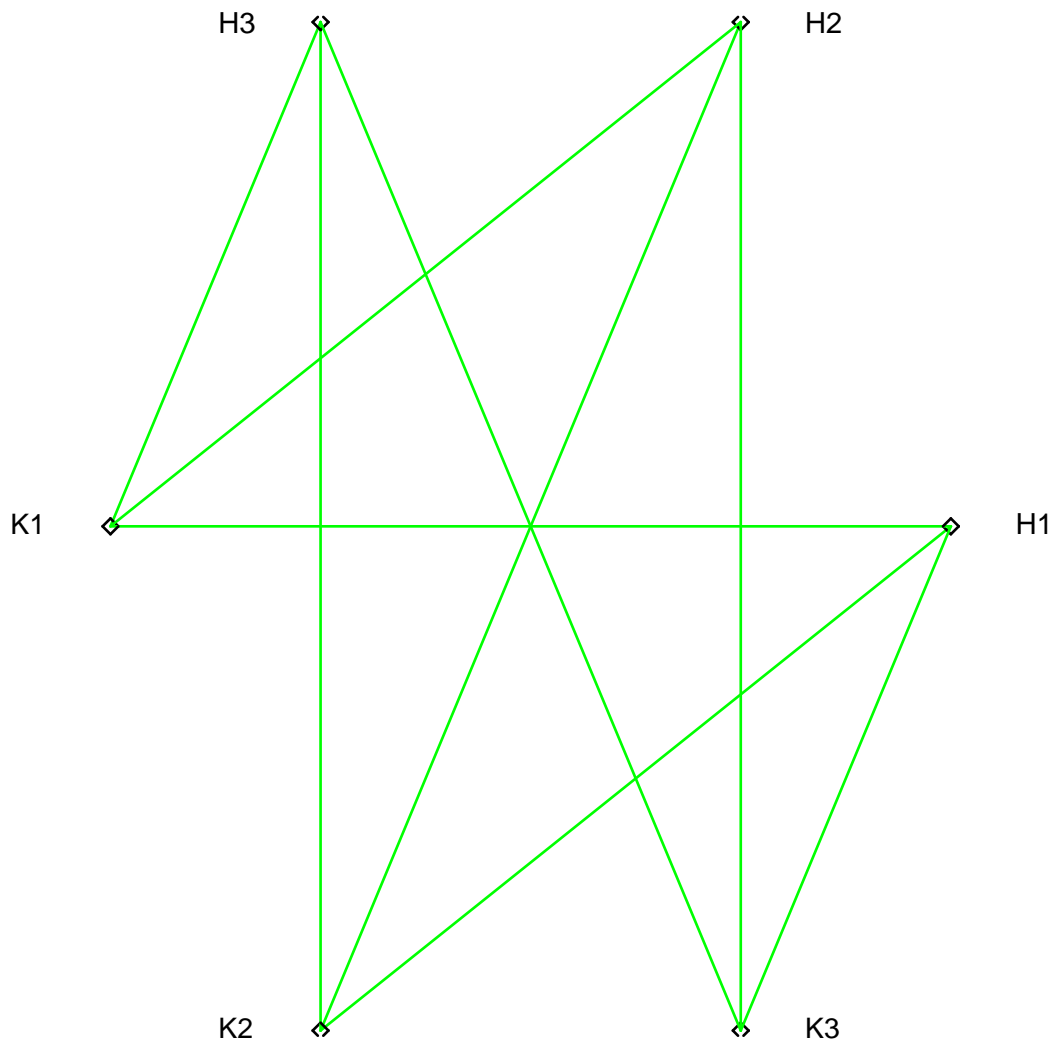
▼ ->7.1.10. Feladat.

▼ ->7.1.11. Feladat.

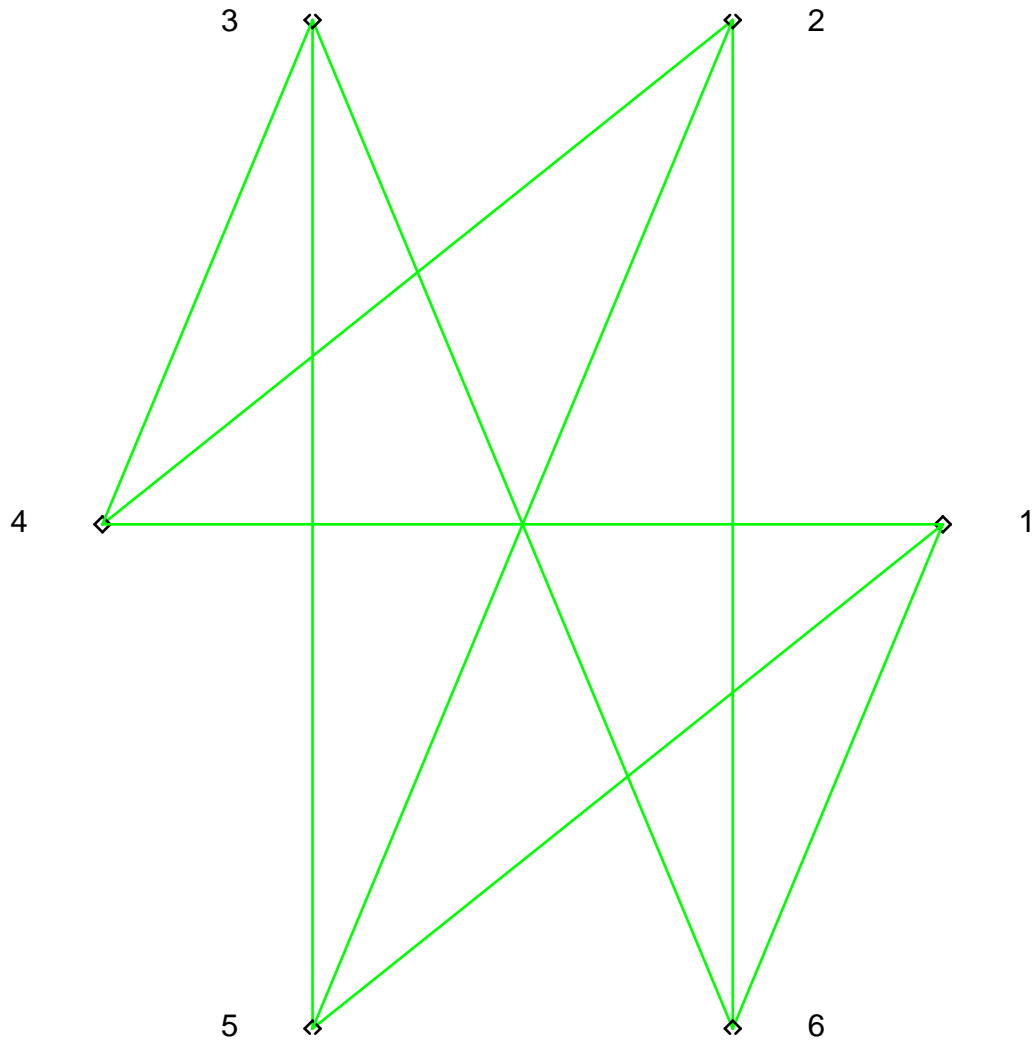
▼ ->7.1.12. Feladat.

▼ **7.1.13. Páros gráfok.**

```
> new(G22):addvertices([H1,H2,H3,K1,K2,K3],G22);connect({H1,
H2,H3},{K1,K2,K3},G22);draw(G22);
      H1, H2, H3, K2, K1, K3
      e1, e2, e3, e4, e5, e6, e7, e8, e9
```



```
> G:=complete(3,3):draw(G);
```



► -> 7.1.14. Feladat.

▼ 7.1.15. Részgráf.

```
> show(G);
table([_Tail = table([], _Counttrees = _Counttrees, _Vertices = ({1, (7.1.15.1)
2, 3, 4, 5, 6}), _Vweight = table(sparse, []),
_EdgeIndex = table(symmetric, [(1, 5) = {e2}, (1, 4) = {e1}, (2,
5) = {e5}, (3, 6) = {e9}, (2, 4) = {e4}, (2, 6) = {e6}, (3,
4) = {e7}, (3, 5) = {e8}, (1, 6) = {e3}])),
_Econnectivity = _Econnectivity, _Emaxname = 9,
_Head = table([], _Eweight = table([e4 = 1, e9 = 1, e7 = 1,
e1 = 1, e5 = 1, e6 = 1, e2 = 1, e8 = 1, e3 = 1]), _Edges = ({e1, e2,
e3, e4, e5, e6, e7, e8, e9}), _Neighbors = table([1 = ({4, 5, 6}),
2 = ({4, 5, 6}), 3 = ({4, 5, 6}), 5 = ({1, 2, 3}), 4 = ({1, 2, 3}),
6 = ({1, 2, 3})]), _Status = ({SIMPLE, BIPARTITE})),
```

```

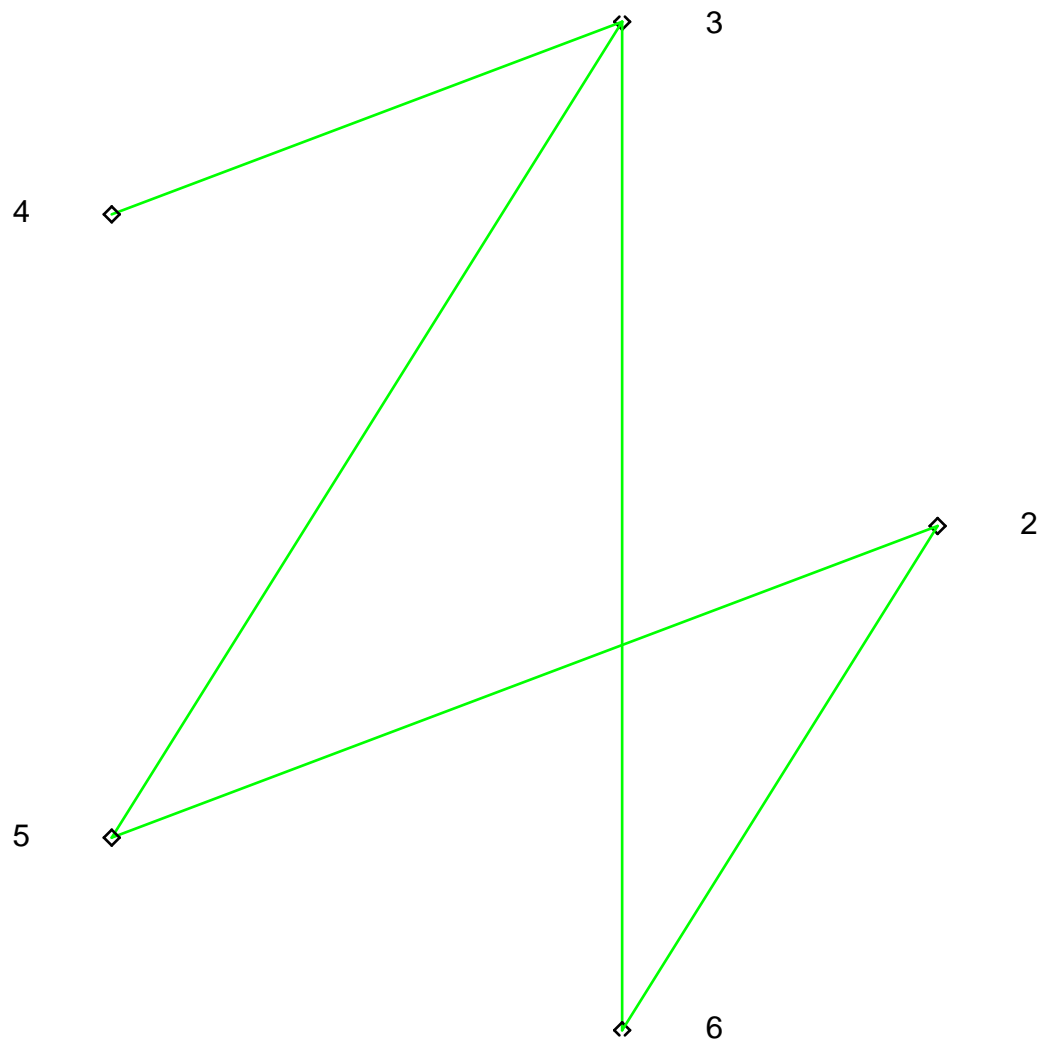
_Ends = table([e4 = ({2, 4}), e9 = ({3, 6}), e7 = ({3, 4}),
e1 = ({1, 4}), e5 = ({2, 5}), e6 = ({2, 6}), e2 = ({1, 5}),
e8 = ({3, 5}), e3 = ({1, 6})]), _Bicomponents = _Bicomponents,
_Countcuts = _Countcuts])

```

```

> delete({e4}, delete({1}, G):vertices(%); edges(%); draw(%));
      {2, 3, 4, 5, 6}
      {e5, e6, e7, e8, e9}

```



```

> show(G1);
table([_Tail = table([]), _Counttrees = _Counttrees,
      _Vertices = ({v1, v2, v3, v5, v4}), _Vweight = table(sparse, []),
      _EdgeIndex = table(symmetric, [(v3, v4) = {e4}, (v1,
v4) = {e3}, v4 = {e5}, (v1, v2) = ({e1, e2})]),
      _Econnectivity = _Econnectivity, _Emaxname = 5,
      _Head = table([], _Eweight = table([e4 = 1, e1 = 1, e5 = 1,
e2 = 1, e3 = 1])), _Edges = ({e1, e2, e3, e4, e5}),
      _Neighbors = table([v4 = ({v1, v3, v4}), v5 = {}, v2 = {v1},

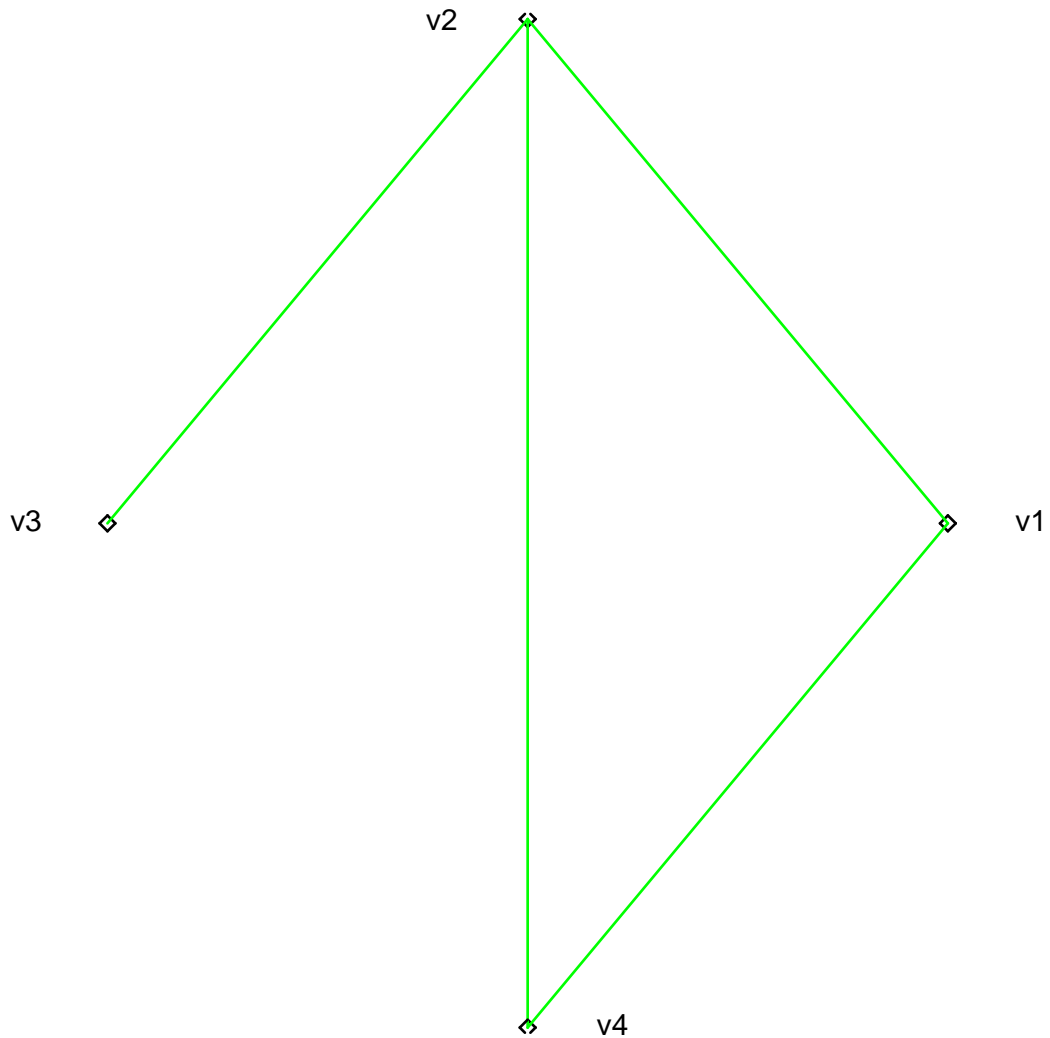
```

(7.1.15.2)



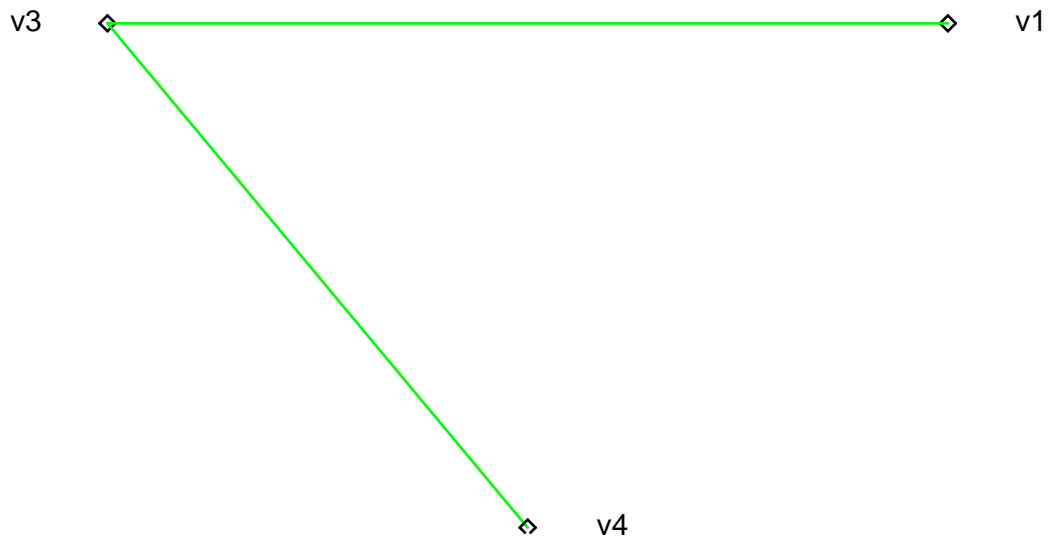
```
v3 = {v4}, v1 = ({v2, v4})), _Status = ({MULTIGRAPH,  
LOOPS}), _Ends = table([e4 = ({v3, v4}), e1 = ({v1, v2}),  
e5 = {v4}, e2 = ({v1, v2}), e3 = ({v1, v4})]),  
_Bicomponents = _Bicomponents, _Countcuts = _Countcuts])
```

```
> new(G3) : addvertex({v1, v2, v3, v4}, G3) ; addedge([ {v1, v2}, {v2,  
v3}, {v1, v4}, {v2, v4}], G3) ; draw(G3) ;  
v1, v2, v3, v4  
e1, e2, e3, e4
```



```
> draw(complement(G3)) ;
```

v2 ◊



```
> induce({v2,v3,v4},G3):draw(%) ;
```

v3



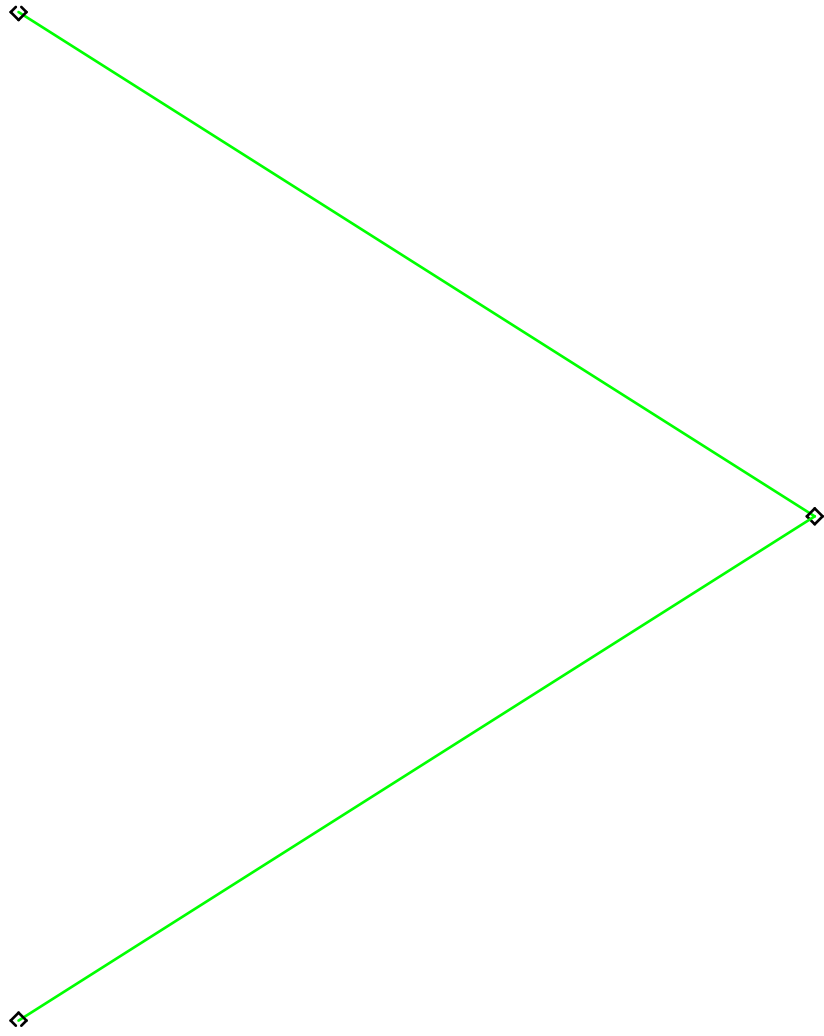
v2

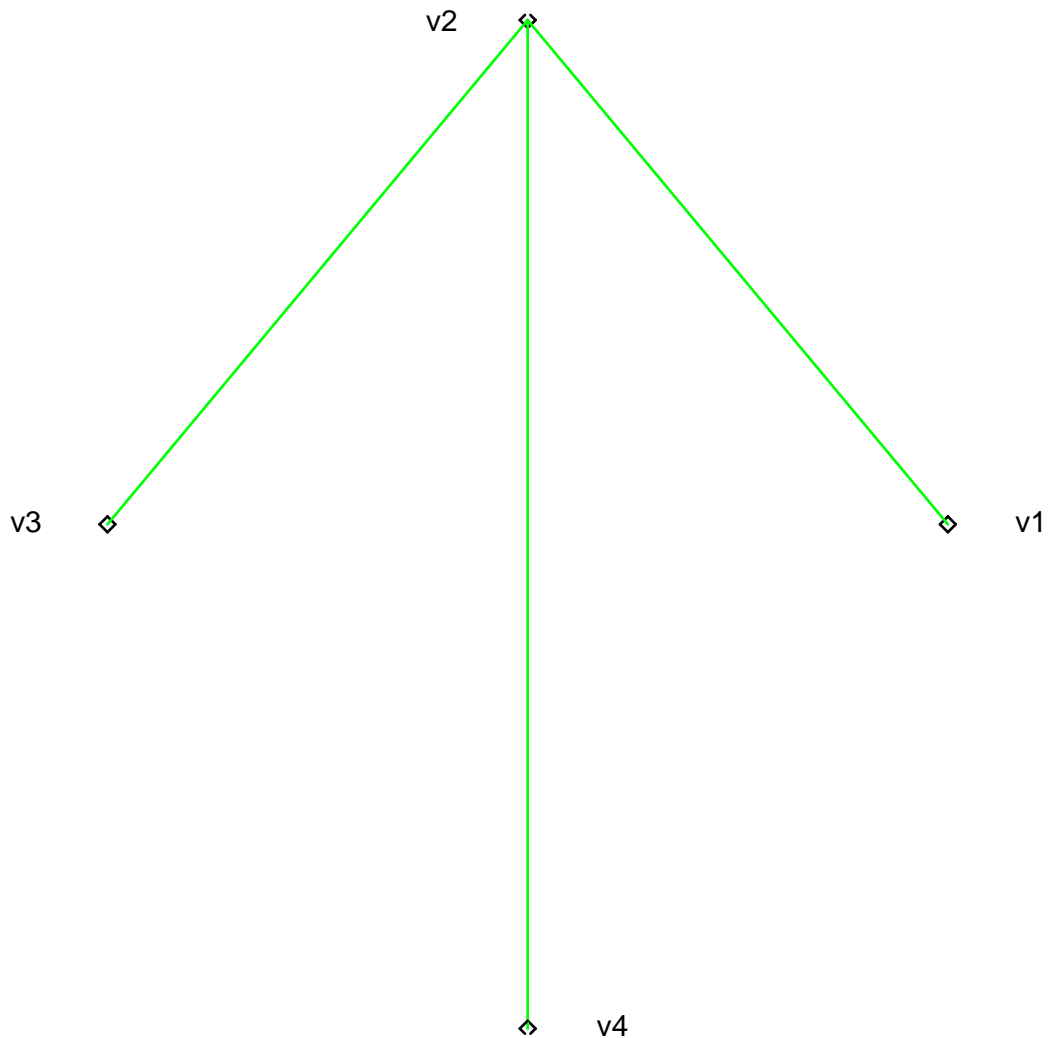


v4



```
> induce({e2,e1,e4},G3):draw(%) ;
```





► -> 7.1.16. Feladat.

▼ -> 7.1.17. Feladat.

▼ -> 7.1.18. Feladat.

▼ 7.1.19. Séták, vonalak, utak, körök.

```
> G4:=void(9):addege(Path(1,2,3,4,5,6,7,3,8,9,8),G4);show(G4);
```

*e1, e2, e3, e4, e5, e6, e7, e8, e9, e10*

```
table([_Tail = table([], _Counttrees = _Counttrees, _Vertices = ({1, (7.1.19.1)
2, 3, 4, 5, 6, 7, 8, 9}), _Vweight = table(sparse, []),
_EdgeIndex = table(symmetric, [(8, 9) = ({e9, e10}), (3,
7) = {e7}, (3, 4) = {e3}, (3, 8) = {e8}, (2, 3) = {e2}, (5,
6) = {e5}, (1, 2) = {e1}, (6, 7) = {e6}, (4, 5) = {e4}]]),
```

```

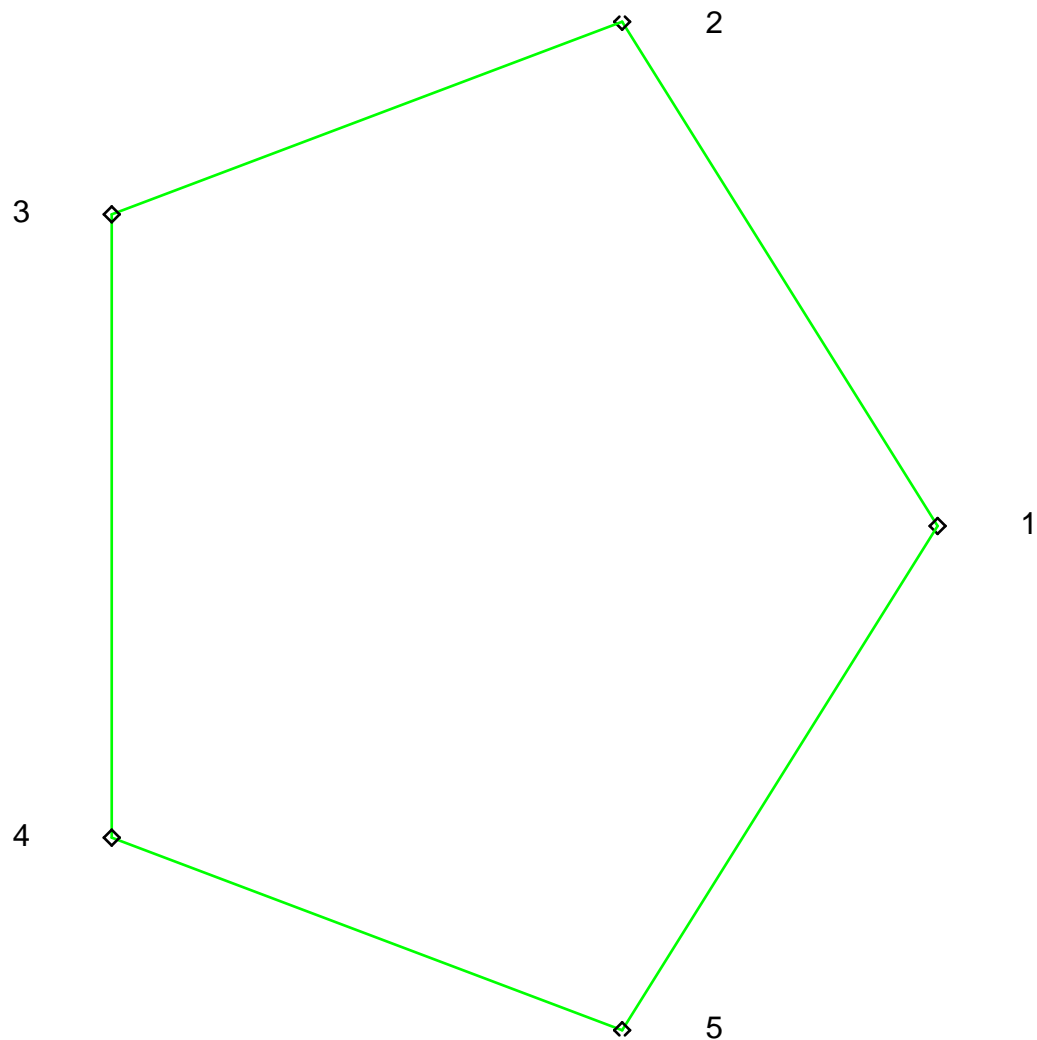
_Econnectivity = _Econnectivity, _Emaxname = 10,
_Head = table([]), _Eweight = table([e4 = 1, e9 = 1, e7 = 1,
e1 = 1, e5 = 1, e6 = 1, e10 = 1, e2 = 1, e8 = 1, e3 = 1]),
_Edges = ({e1, e2, e3, e4, e5, e6, e7, e8, e9, e10}),
_Neighbors = table([1 = {2}, 2 = ({1, 3}), 3 = ({2, 4, 7, 8}),
5 = ({4, 6}), 4 = ({3, 5}), 7 = ({3, 6}), 6 = ({5, 7}), 8 = ({3,
9}), 9 = {8}]), _Status = {MULTIGRAPH},
_Ends = table([e4 = ({4, 5}), e9 = ({8, 9}), e7 = ({3, 7}),
e1 = ({1, 2}), e5 = ({5, 6}), e6 = ({6, 7}), e10 = ({8, 9}),
e2 = ({2, 3}), e8 = ({3, 8}), e3 = ({3, 4})]),
_Bicomponents = _Bicomponents, _Countcuts = _Countcuts]

```

```

> G:=void(5):addege(Cycle(1,2,3,4,5),G);draw(G);
e1, e2, e3, e4, e5

```



► 7.1.20. Állítás.

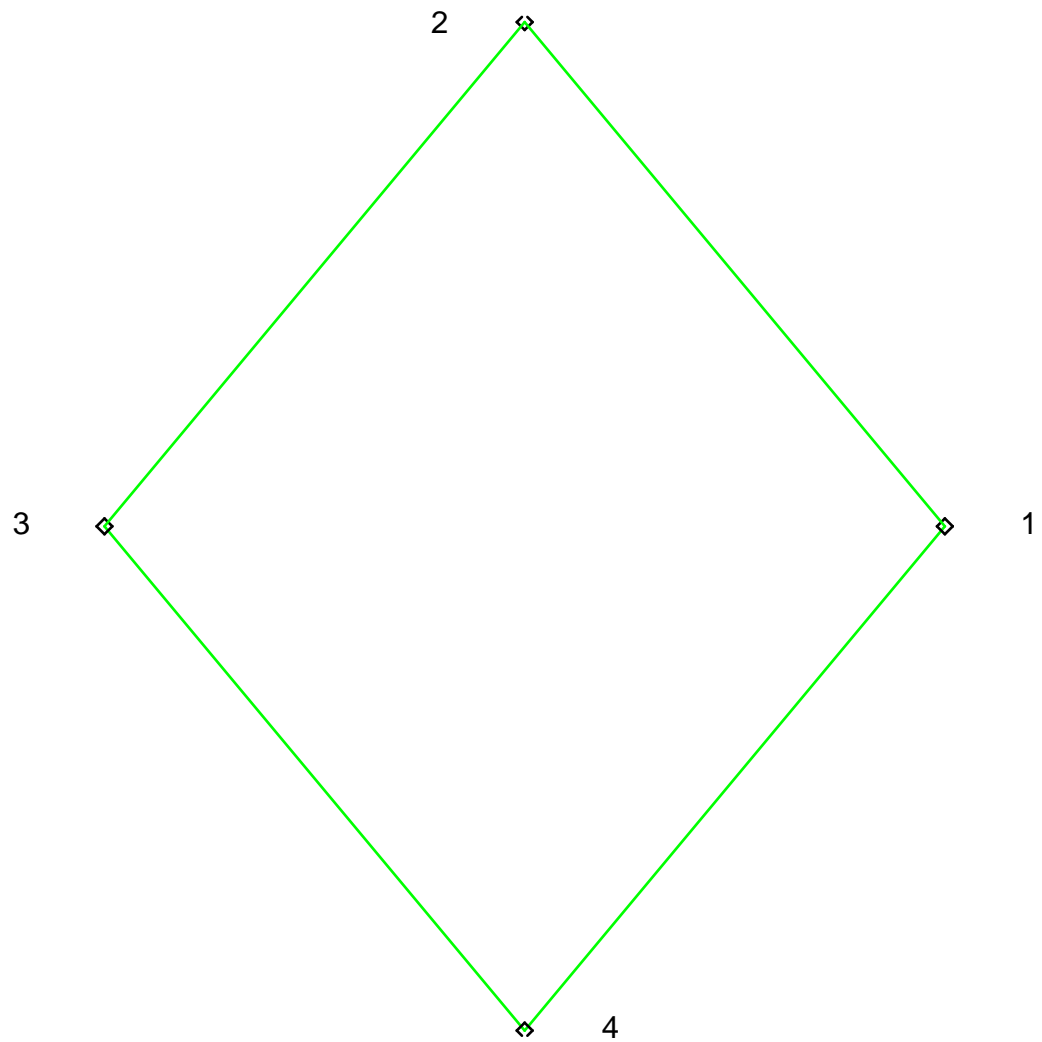
- ▶ 7.1.21. *Állítás.*
- ▶ ->7.1.22. *Feladat.*
- ▶ ->7.1.23. *Feladat.*
- ▼ 7.1.24. *Összefüggőség.*

```
> G:=random(12,6):ends(G);components(G);  
      {{2,3},{6,8},{3,8},{4,6},{2,10},{2,12}}  
      {{1},{5},{7},{9},{11},{2,3,4,6,8,10,12}}
```

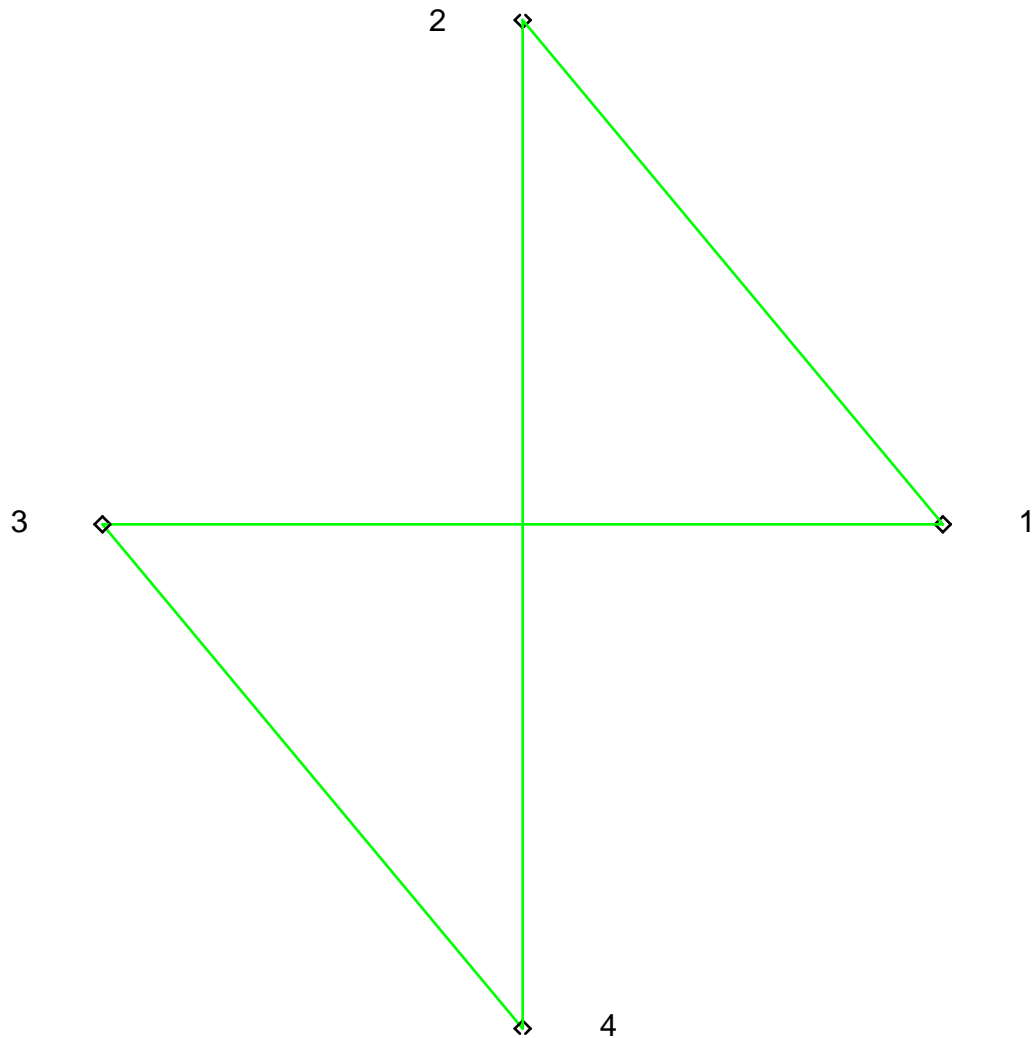
(7.1.24.1)

- ▶ ->7.1.25. *Feladat.*
- ▶ ->7.1.26. *Feladat.*
- ▶ 7.1.27. *Feladat.*
- ▶ 7.1.28. *Fák.*
- ▶ 7.1.29. *Tétel.*
- ▶ 7.1.30. *Tétel.*
- ▶ 7.1.31. *Tétel.*
- ▶ ->7.1.32. *Feladat.*
- ▶ ->7.1.33. *Feladat.*
- ▼ 7.1.34. *Feladat.*
- ▶ \*7.1.35. *Feladat.*
- ▼ 7.1.36. *Feszítőfa.*

```
> G51:=cycle(4):draw(G51);
```



```
> G52:=void(4):addege(Cycle(1,2,4,3),G52);draw(G52);  
e1, e2, e3, e4
```



```
> spantree(G52) : edges(%) ; counttrees(G52) ;
      {e1, e2, e4}
      4
```

(7.1.36.1)

▼ 7.1.37. Állítás.

▼ 7.1.38. Állítás.

▼ 7.1.39. Megjegyzés.

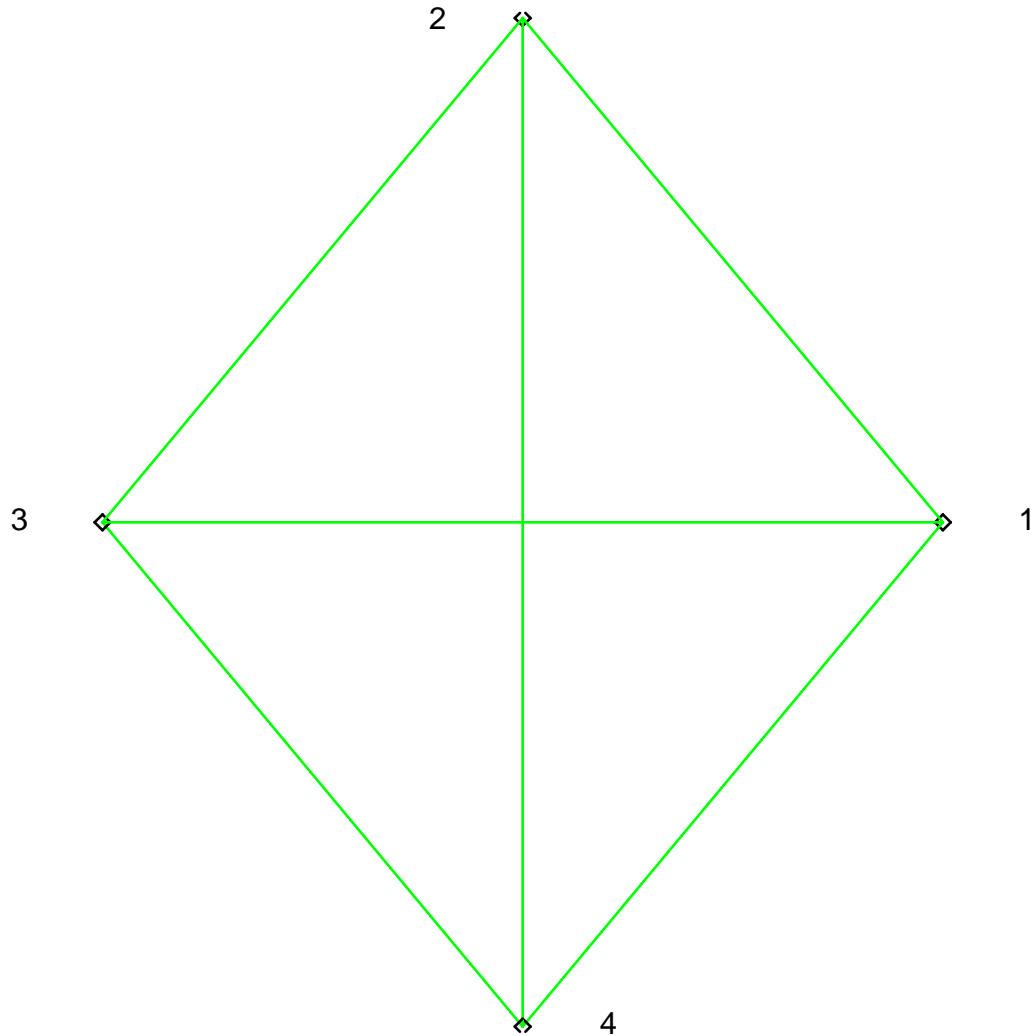
```
> G6:=tetrahedron() : show(G) ; cyclebase(G6) ; draw(G6) ;
table([_Tail = table([ ]), _Counttrees = _Counttrees, _Vertices = ({1, 2, 3, 4,
5, 6, 7, 8, 9, 10, 11, 12}), _Vweight = table(sparse, [ ]),
_EdgeIndex = table(symmetric, [(6, 8) = {e2}, (4, 6) = {e4}, (3,
8) = {e3}, (2, 3) = {e1}, (2, 12) = {e6}, (2, 10) = {e5}]),
_Econnectivity = _Econnectivity, _Emaxname = 6, _Head = table([ ]),
```



```

_Eweight = table([e4 = 1, e1 = 1, e5 = 1, e6 = 1, e2 = 1, e3 = 1]),
_Edges = ({e1, e2, e3, e4, e5, e6}), _Neighbors = table([1 = {}, 2 = ({3,
10, 12}), 3 = ({2, 8}), 5 = {}, 4 = {6}, 7 = {}, 6 = ({4, 8}), 10 = {2},
11 = {}, 8 = ({3, 6}), 9 = {}, 12 = {2}]), _Ends = table([e4 = ({4, 6}),
e1 = ({2, 3}), e5 = ({2, 10}), e6 = ({2, 12}), e2 = ({6, 8}), e3 = ({3,
8})]), _Bicomponents = _Bicomponents, _Countcuts = _Countcuts]
    {{e2, e3, e6}, {e1, e3, e4, e6}, {e1, e3, e5}}

```



► 7.1.40. Vágás.

▼ 7.1.41. Állítás.

```
> cycle(4):countcuts(%)
```

6

(7.1.41.1)

► 7.1.42. Erdő.

► ->7.1.43. Feladat.

▶ **7.1.44. Euler-vonal.**

▶ **7.1.45. Állítás.**

▶ -> **7.1.46. Feladat.**

▶ -> **7.1.47. Feladat.**

▼ **7.1.48. Hamilton-út.**

▶ -> **7.1.49. Feladat.**

▶ -> **7.1.50. Feladat.**

▶ **7.1.51. Feladat.**

▶ -> **7.1.52. Feladat.**

▶ -> **7.1.53. Feladat.**

▶ -> **7.1.54. Feladat.**

▶ **7.1.55. Feladat.**

▶ **7.1.56. Feladat.**

▶ **7.1.57. Feladat.**

▶ **\*7.1.58. Feladat: Dirac tétele.**

▶ **\*7.1.59. Feladat.**

▼ **7.1.60. Címkezett és súlyozott gráfok.**

```
> new(G9) : addvertex([v1,v2,v3,v4], weights=[2,4,6,8], G9);  
  addedge([ {v1,v2}, {v2,v3}, {v1,v3}, {v3,v4} ], weights=[1,1,1,3]  
  , G9); show(G9);
```

$v1, v2, v3, v4$

$e1, e2, e3, e4$

```
table([_Tail = table([ ]), _Counttrees = _Counttrees, (7.1.60.1)  
  _Vertices = ({v1, v2, v3, v4}), _Vweight = table(sparse, [v4 = 8,  
  v2 = 4, v3 = 6, v1 = 2]), _EdgeIndex = table(symmetric, [(v3,  
  v4) = {e4}, (v2, v3) = {e2}, (v1, v2) = {e1}, (v1, v3) = {e3}]),  
  _Econnectivity = _Econnectivity, _Emaxname = 4,  
  _Head = table([ ]), _Eweight = table([e4 = 3, e1 = 1, e2 = 1,  
  e3 = 1]), _Edges = ({e1, e2, e3, e4}),  
  _Neighbors = table([v4 = {v3}, v2 = ({v1, v3}), v3 = ({v1, v2,  
  v4}), v1 = ({v2, v3})]), _Ends = table([e4 = ({v3, v4}),  
  e1 = ({v1, v2}), e2 = ({v2, v3}), e3 = ({v1, v3})]),  
  _Bicomponents = _Bicomponents, _Countcuts = _Countcuts])
```

▼ **7.1.61. Mohó algoritmus minimális összsúlyú feszítőerdő konstrukciójára.**

```
> spantree(G9):ends(%);  
    {{v1, v2}, {v3, v4}, {v1, v3}}
```

 (7.1.61.1)

## ▼ 7.1.62. Mohó algoritmusok.

▶ 7.1.63. *Feladat: minimális összsúlyú feszítőfa fanövesztéssel.*

▶ 7.1.64. *Feladat: piros-kék algoritmus.*

▶ \*7.1.65. *Feladat: a kínai postás-probléma.*

▶ \*7.1.66. *Feladat: az utazó ügynök problémája.*

▶ 7.1.67. *További feladatok.*

## ▼ 7.2. Irányított gráfok

### ▼ 7.2.1. Irányított gráfok.

```
> restart;with(networks);  
[acycpoly, addedge, addvertex, adjacency, allpairs, ancestor, arrivals, (7.2.1.1)  
 bicomponents, charpoly, chrompoly, complement, complete,  
 components, connect, connectivity, contract, countcuts, counttrees,  
 cube, cycle, cyclebase, daughter, degreeseq, delete, departures,  
 diameter, dinic, djspantree, dodecahedron, draw, draw3d,  
 duplicate, edges, ends, eweight, flow, flowpoly, fundcyc, getlabel,  
 girth, graph, graphical, gsimp, gunion, head, icosahedron,  
 incidence, incident, indegree, induce, isplanar, maxdegree,  
 mincut, mindegree, neighbors, new, octahedron, outdegree, path,  
 petersen, random, rank, rankpoly, shortpathtree, show, shrink,  
 span, spanpoly, spantree, tail, tetrahedron, tuttepoly, vdegree,  
 vertices, void, vweight]
```

```
> G:=void(6):addege([[1,2],[2,4],[1,3],[3,6],[2,6],[1,5]],G)  
;  
tail(e1,G);head(e1,G);  
    e1, e2, e3, e4, e5, e6  
    1  
    2
```

 (7.2.1.2)

```
> indegree(2,G);outdegree(2,G);  
    1  
    2
```

 (7.2.1.3)

```
> addedge([1,2],G);tail(%,G);head(%,G);
```

e7

1

2

(7.2.1.4)

> **show(G);**

```
table([_Bicomponents = _Bicomponents, _Vweight = table(sparse,  
  []), _Ends = table([e3 = ({1, 3}), e6 = ({1, 5}), e2 = ({2, 4}),  
  e5 = ({2, 6}), e4 = ({3, 6}), e1 = ({1, 2}), e7 = ({1, 2})]),  
  _Tail = table([e3 = 1, e6 = 1, e2 = 2, e5 = 2, e4 = 3, e1 = 1,  
  e7 = 1]), _Econnectivity = _Econnectivity, _Vertices = ({1, 2, 3, 4,  
  5, 6}), _EdgeIndex = table(symmetric, [(2, 6) = {e5}, (3,  
  6) = {e4}, (1, 2) = ({e1, e7}), (1, 5) = {e6}, (1, 3) = {e3}, (2,  
  4) = {e2}]), _Countcuts = _Countcuts, _Counttrees = _Counttrees,  
  _Head = table([e3 = 3, e6 = 5, e2 = 4, e5 = 6, e4 = 6, e1 = 2,  
  e7 = 2]), _Neighbors = table([1 = ({2, 3, 5}), 2 = ({1, 4, 6}),  
  3 = ({1, 6}), 5 = {1}, 4 = {2}, 6 = ({2, 3})]),  
  _Status = ({MULTIGRAPH, DIRECTED}), _Emaxname = 7,  
  _Eweight = table([e3 = 1, e6 = 1, e2 = 1, e5 = 1, e4 = 1, e1 = 1,  
  e7 = 1]), _Edges = ({e1, e2, e3, e4, e5, e6, e7}])])
```

(7.2.1.5)

- ▶ **7.2.2. Példa.**
- ▶ -> **7.2.3. Feladat.**
- ▶ -> **7.2.4. Feladat.**
- ▶ -> **7.2.5. Feladat.**
- ▶ **7.2.6. Feladat.**
- ▶ **7.2.7. Feladat.**
- ▶ **7.2.8. Feladat.**
- ▶ **7.2.9. Irányított gráfok izomorfiája.**
- ▼ **7.2.10. Példák.**
- ▼ **7.2.11. Véges gráfok éllistas ábrázolása.**
- ▶ **7.2.12. Irányított részgráf.**
- ▶ **7.2.13. Irányított séták, vonalak, utak és körök.**
- ▼ **\*7.2.14. Topologikus rendezés.**
- ▶ **7.2.15. Erős összefüggőség.**
- ▶ **7.2.16. Irányított fa.**

- ▶ **7.2.17. König-lemma.**
- ▼ **\*7.2.18. Kupac.**
- ▼ **\*7.2.19. Kupacrendezés.**
- ▼ **\*7.2.20. B-fa.**
- ▶ **\*7.2.21. Oszd meg és uralkodj.**
- ▼ **\*7.2.22. Dijkstra módszere.**
- ▼ **\*7.2.23. Megjegyzés.**
- ▶ **\*7.2.24. Dinamikus programozás.**
- ▼ **\*7.2.25. Feladat.**
- ▶ **\*7.2.26. Feladat.**
- ▶ **\*7.2.27. Feladat.**
- ▼ **\*7.2.28. Feladat.**
- ▼ **\*7.2.29. Szélességi bejárás.**
- ▼ **\*7.2.30. Mélységi bejárás.**
- ▼ **\*7.2.31. Feladat: Warshall-Floyd-algoritmus.**
- ▼ **\*7.2.32. Feladat.**
- ▼ **\*7.2.33. Feladat: erős komponensek meghatározása.**
- ▼ **\*7.2.34. PERT.**
- ▼ **\*7.2.35. Feladat.**
- ▼ **\*7.2.36. Folyamprobléma.**
- ▶ **\*7.2.37. Lemma.**
- ▶ **\*7.2.38. Ford-Fulkerson-tétel (maximális folyam, minimális vágás tétel).**
- ▶ **\*7.2.39. Edmonds-Karp-heurisztika.**

▼ **\*7.2.40. Dinic módszere.**

▶ **\*7.2.41. Feladat.**

▶ **\*7.2.42. Feladat.**

▶ **\*7.2.43. Feladat: általánosított folyamprobléma.**

▶ **\*7.2.44. Feladat: Menger tétele elvágó élhalmazra.**

▶ **\*7.2.45. Feladat: Menger tétele elvágó csúcshalmazra.**

▶ **\*7.2.46. Feladat: König tétele.**

▶ **\*7.2.47. Gráfok rajzolhatósága.**

▶ **\*7.2.48. Állítás.**

▶ **\*7.2.49. Segédteétel.**

▶ **\*7.2.50. Tétel.**

▶ **->7.2.51. Feladat.**

▶ **->7.2.52. Feladat.**

▶ **\*7.2.53. Tartományok.**

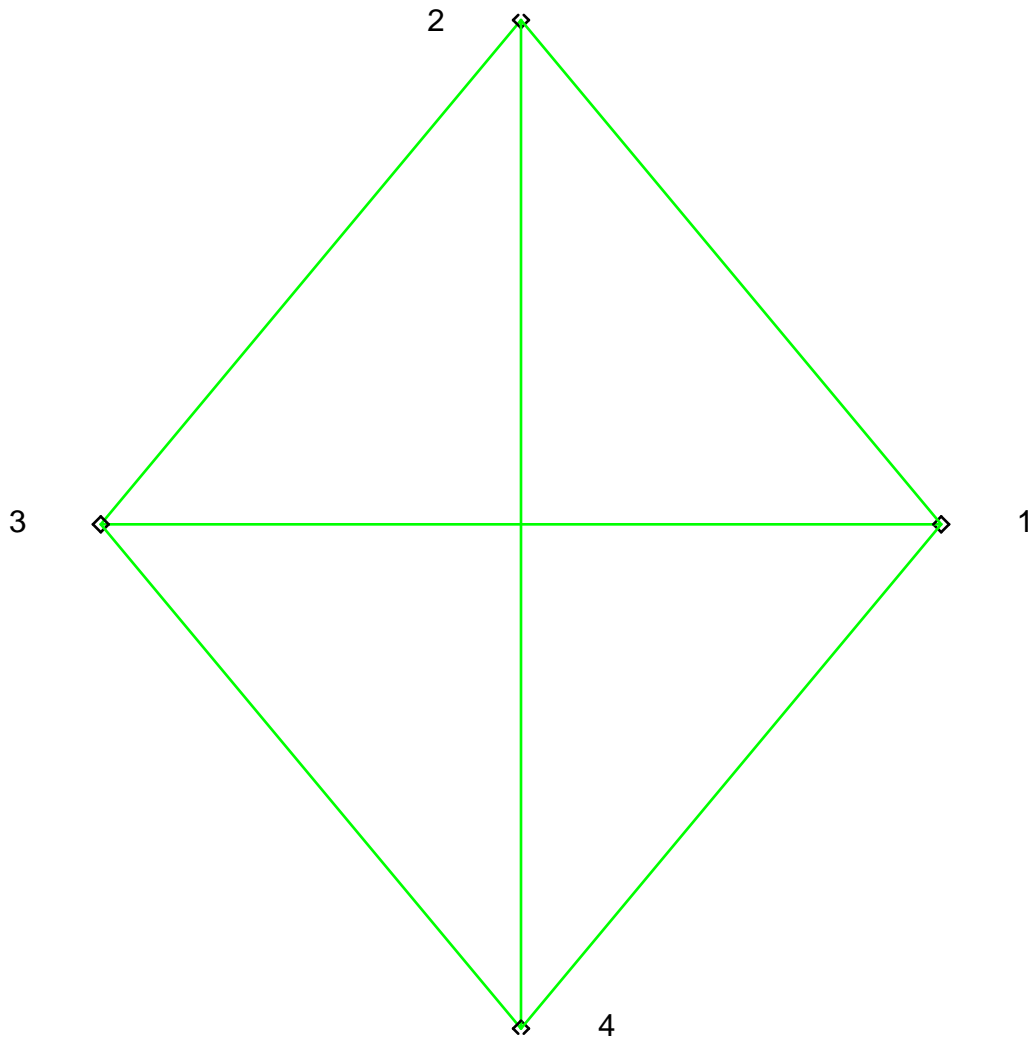
▶ **\*7.2.54. Euler tétele.**

▶ **\*7.2.55. Megjegyzés.**

▶ **\*7.2.56. Gráfok topologikus izomorfizmusa.**

▼ **\*7.2.57. Kuratowski tétele.**

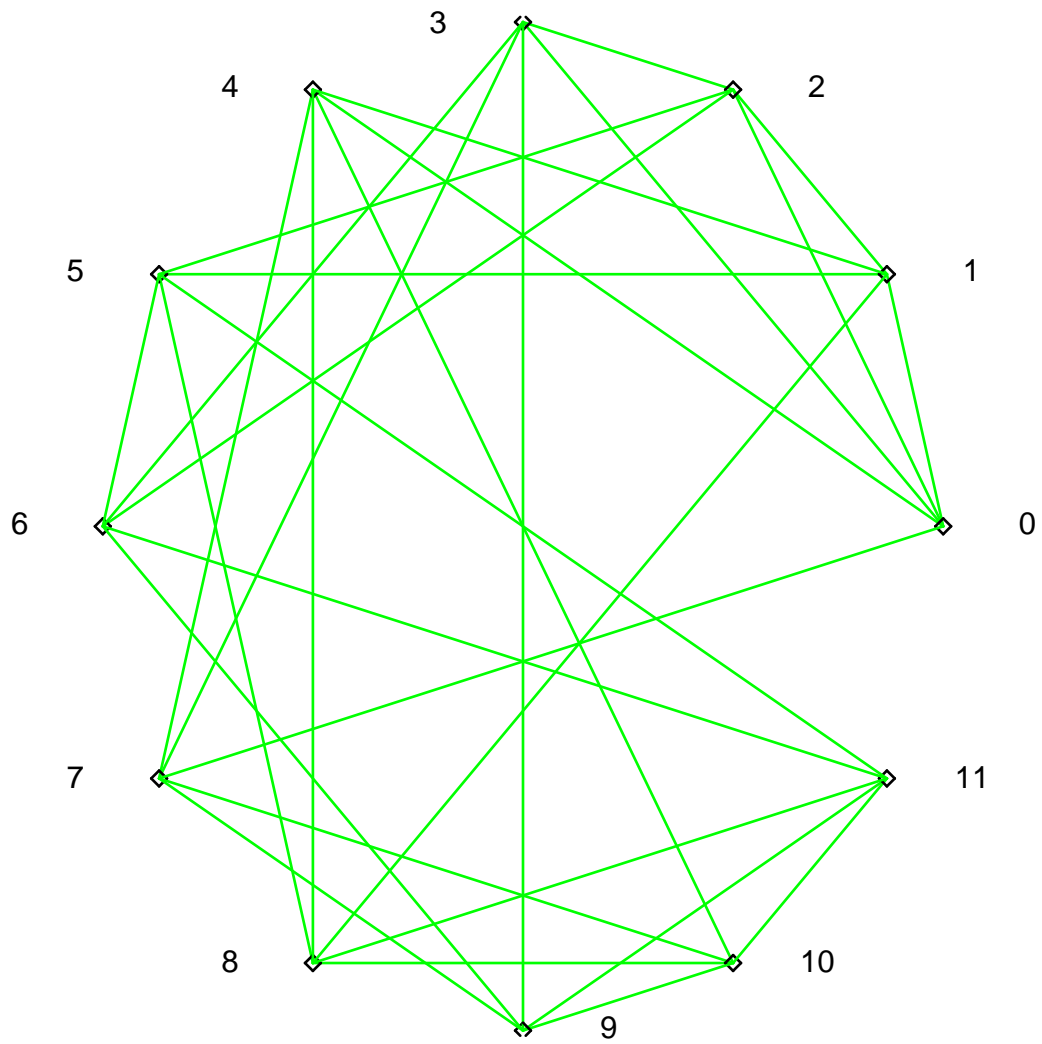
```
> G:=tetrahedron():draw(G);isplanar(G);
```



*true*

(7.2.57.1)

```
> G:=icosahedron():draw(G);isplanar(G);
```

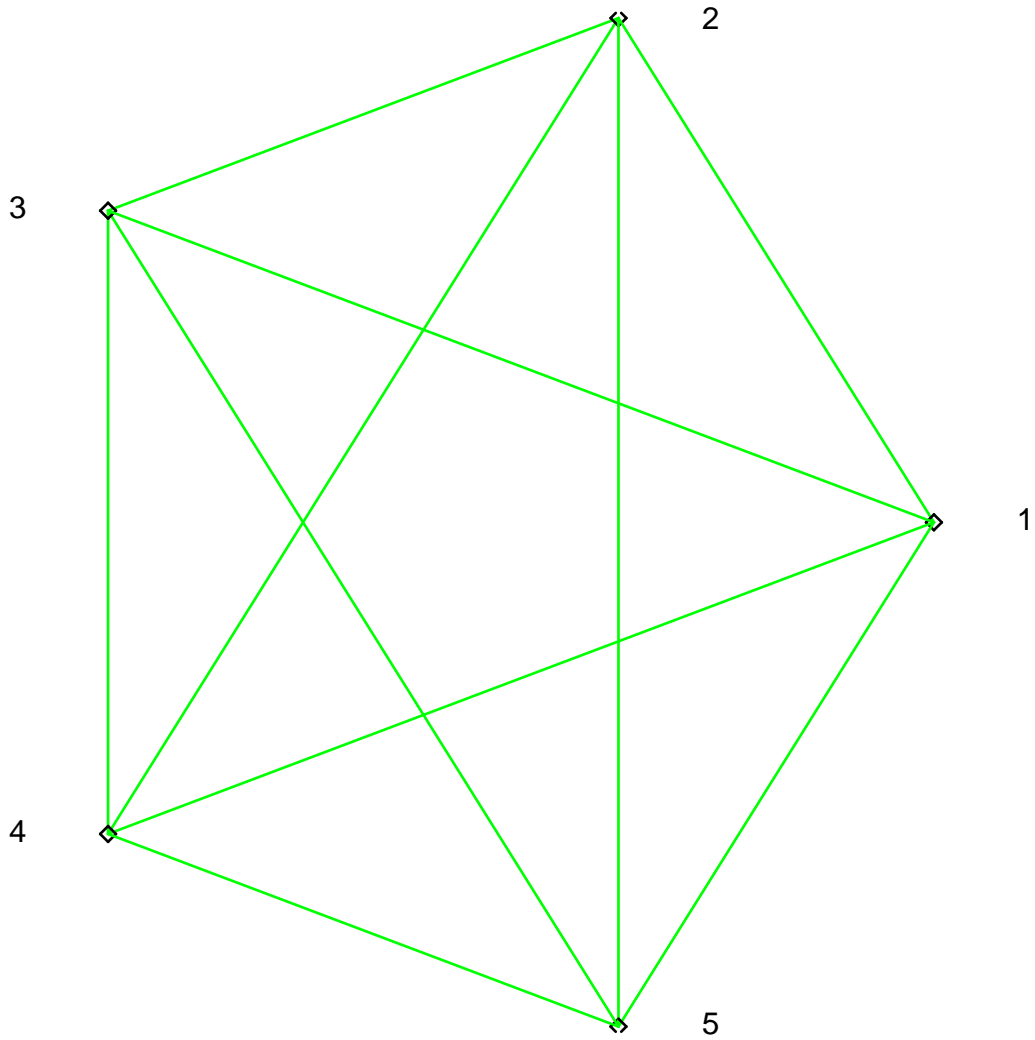


*true*

(7.2.57.2)

```
> G:=complete(5):draw(G);isplanar(G);
```

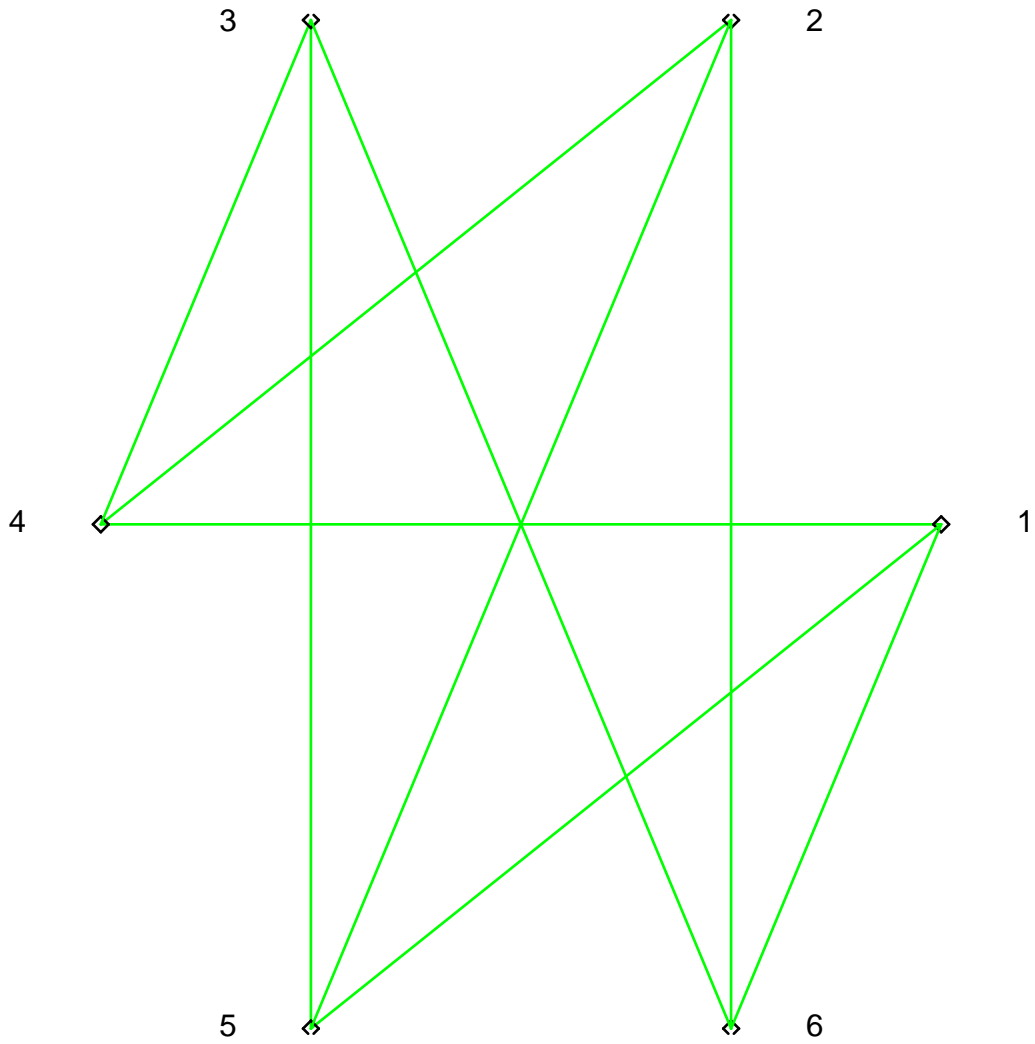




*false*

(7.2.57.3)

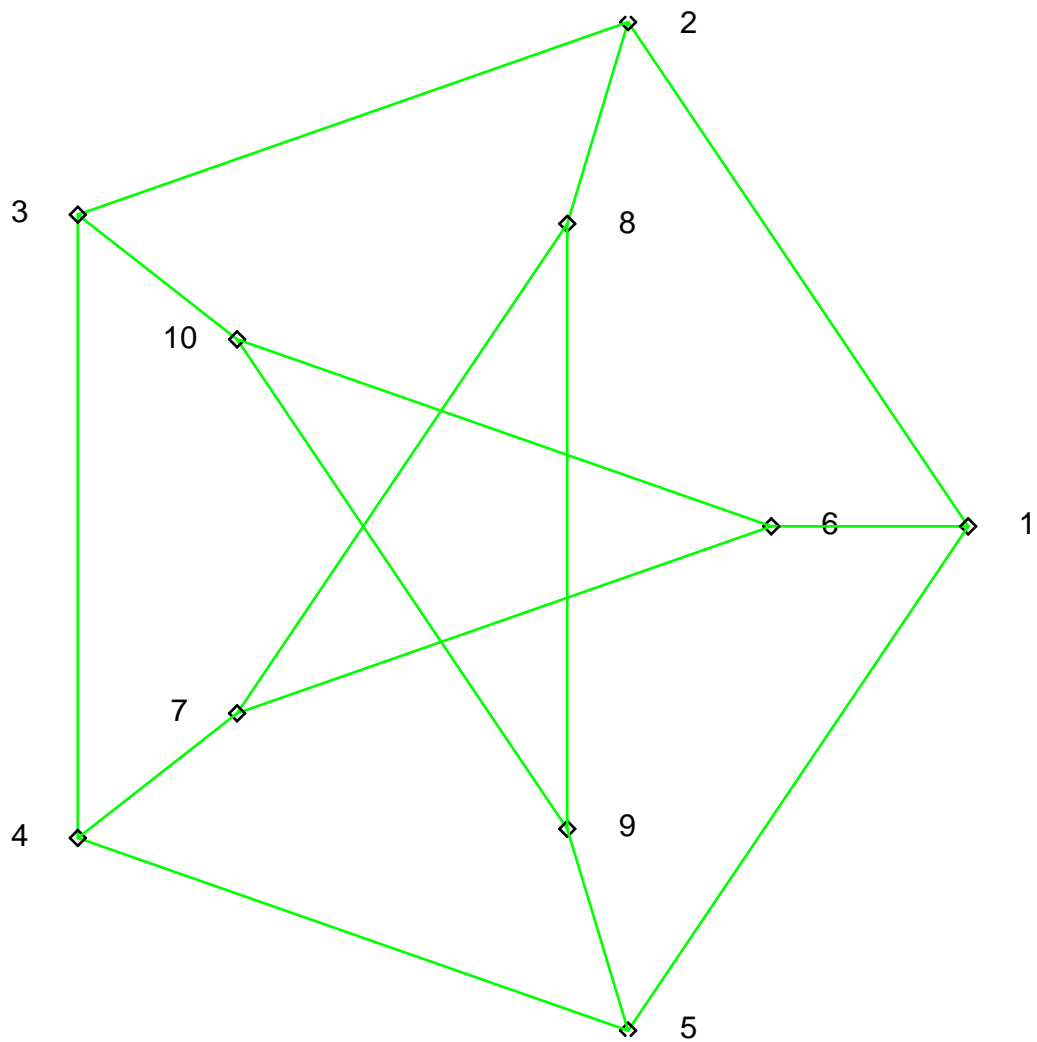
```
> G:=complete(3,3):draw(G);isplanar(G);
```



*false*

(7.2.57.4)

```
> G:=petersen():draw(G);isPlanar(G);
```



*false*

(7.2.57.5)

▼ **\*7.2.58. Feladat.**

▶ **\*7.2.59. Feladat.**

▶ **\*7.2.60. Feladat.**

▶ **\*7.2.61. Feladat.**

▶ **\*7.2.62. Feladat.**

▶ **7.2.63. Kromatikus szám.**

▶ **->7.2.64. Feladat.**

▶ **7.2.65. Feladat.**

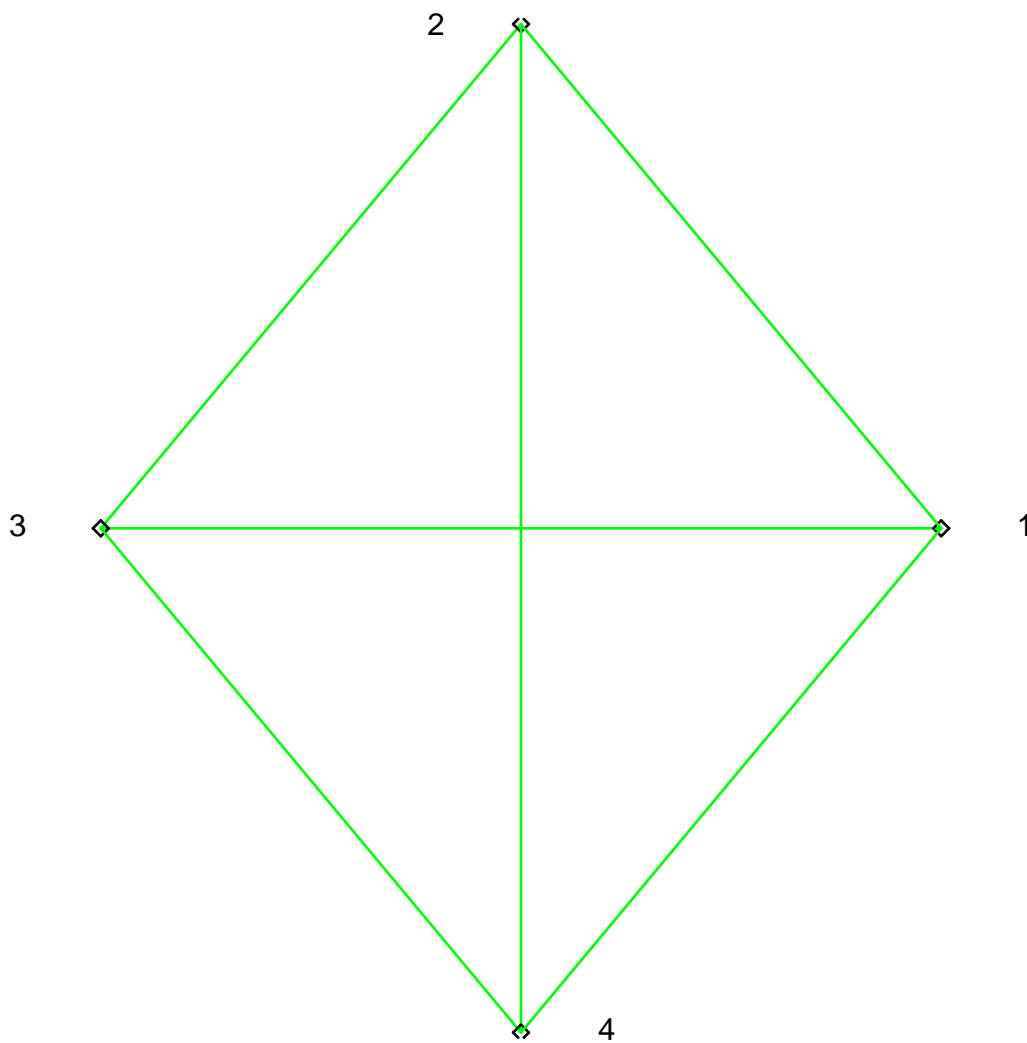
▶ **7.2.66. Feladat.**

▶ **7.2.67. Feladat.**

▶ **7.2.68. Feladat.**

▼ 7.2.69. Gráfok mátrixai.

> `G:=tetrahedron();draw(G);adjacency(G);incidence(G);`



$$\begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 \end{bmatrix}$$

(7.2.69.1)

▼ *7.2.70. Feladat.*

▶ *7.2.71. További feladatok.*

▶ **8. Algebra**

▶ **9. Kódolás**

▶ **10. Algoritmusok**